

ATTORNEY DOCKET NO.
064749.0141

PATENT APPLICATION
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IN THE CLAIMS

For the convenience of the Examiner, all pending claims of the present Application are shown below in numerical order whether or not an amendment has been made and applying the revised format guidelines of 37 C.F.R. 1.121.

1. (Currently Amended) A computerized method for assigning observations comprising:

receiving a plurality of first observations indicative of respective physical ~~parameters~~ positions observed by a first sensor system and receiving a plurality of second observations indicative of respective physical ~~parameters~~ positions observed by a second sensor system;

assigning, by a computer, a set of pairs of the first and second observations predicted to correspond to the same physical ~~parameter~~ position, the assigning comprising:

receiving a cost function that specifies a cost for each assigned pair, the cost not independent of the assignment of any other assigned pairs in the set of assigned pairs; and

determining the set of assigned pairs corresponding to an optimal value for the cost function by calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations.

2. (Original) The method of Claim 1, wherein the directed graph comprises a plurality of nodes each representing an assignment hypothesis, the plurality of nodes comprising a root node, wherein each node except for the root node has an associated input arc representing an assignment decision and wherein the length of each input arc is representative of a change in an assignment score resulting from the assignment decision, wherein the plurality of nodes are grouped in a plurality of stages.

3. (Original) The method of Claim 1, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a network shortest path algorithm.

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4. (Original) The method of Claim 1, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a Dijkstra algorithm.

5. (Previously Presented) The method of Claim 1, wherein the cost function is

$$J_i = \bar{x}^T R^{-1} \bar{x} - \sum_{i=1}^I \left\{ \frac{\delta x_i^T S_i^{-1} \delta x_i + \ln[S_i]}{\bar{g}} - \ln(d_{\min}) \right\} + \begin{cases} a(i) \neq 0 \\ a(i) = 0 \end{cases} + \begin{cases} \ln([2\pi]^M |R|) & n_a = 0 \\ 0 & n_a > 0 \end{cases}$$

wherein

- J_i = Assignment score
- \bar{x} = Estimate of relative bias
- R = Relative registration covariance matrix
- δx_i = State vector difference = $A_i - B_{a(i)} - \bar{x}$
- S_i = Residual error covariance for pair A_i and $B_{a(i)}$
- d_{\min} = Minimum determinant of a residual error matrix
- \bar{g} = Gate value
- M = Number of first observations
- n_a = Number of non-zero entries in a
- a = Assignment vector: $a_{(i)} > 0 \rightarrow A_i$ is assigned to $B_{a(i)}$
- A_i = The plurality of first observations
- $B_{a(i)}$ = The plurality of second observations assigned to A_i

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6. (Original) The method of Claim 5, wherein the relative bias, \bar{x} , of the cost function is a simple bias.
7. (Original) The method of Claim 5, wherein the relative bias, \bar{x} , of the cost function is a functional bias.
8. (Original) The method of Claim 1, wherein assigning, by a computer, comprises assigning by a processor operable to execute a computer program stored on a computer readable medium.
9. (Original) The method of Claim 1, wherein assigning, by a computer, comprises assigning by an application specific integrated circuit.
10. (Original) The method of Claim 1, wherein assigning, by a computer, comprises assigning by a digital signal processor.

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11. (Currently Amended) A computerized method for determining the Nbest observation assignments comprising:

receiving a plurality of first observations indicative of respective physical parameters positions observed by a first sensor system and receiving a plurality of second observations indicative of respective physical parameters positions observed by a second sensor system;

determining, by a computer, one or more sets of pairs of the first and second observations predicted to correspond to the same physical parameter position, the determining comprising:

receiving a cost function that specifies a cost for each assigned pair;

determining a set of assigned pairs corresponding to an optimal value for the cost function by calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of corresponding first and second observations; and

repeating the determining act until a desired number of best observation assignments is determined.

12. (Original) The method of Claim 11, wherein the cost specified by the cost function for each assigned pair is not independent of the assignment of any other assigned pairs in the respective set of assigned pairs.

13. (Original) The method of Claim 11, wherein the directed graph comprises a plurality of nodes each representing an assignment hypothesis, the plurality of nodes comprising a root node, wherein each node except for the root node has an associated input arc representing an assignment decision and wherein the length of each input arc is representative of a change in an assignment score resulting from the assignment decision, wherein the plurality of nodes are grouped in a plurality of stages.

14. (Original) The method of Claim 11, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a network shortest path algorithm.

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15. (Original) The method of Claim 11, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a Dijkstra algorithm.

16. (Previously Presented) The method of Claim 11, wherein the cost function is

$$J_i - \bar{x}^T R^{-1} \bar{x} - \sum_{i=1}^M \left\{ \frac{\delta x_i^T S_i^{-1} \delta x_i + \ln \|S_i\| - \ln(d_{\min})}{\bar{g}} \quad \begin{matrix} a(i) \neq 0 \\ a(i) = 0 \end{matrix} \right\} + \left\{ \begin{matrix} \ln([2\pi]^M |R|) & n_a = 0 \\ 0 & n_a > 0 \end{matrix} \right\}$$

wherein J_i = Assignment score
 \bar{x} = Estimate of relative bias

R = Relative registration covariance matrix

δx_i = State vector difference = $A_i - B_{a(i)} - \bar{x}$

S_i = Residual error covariance for pair A_i and $B_{a(i)}$

d_{\min} = Minimum determinant of a residual error matrix

\bar{g} = Gate value

M = Number of first observations

n_a = Number of non-zero entries in a

a = Assignment vector: $a_{(i)} > 0 \rightarrow A_i$ is assigned to $B_{a(i)}$

A_i = The plurality of first observations

$B_{a(i)}$ = The plurality of second observations assigned to A_i

17. (Original) The method of Claim 16, wherein the relative bias, \bar{x} , of the cost function is a simple bias.

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18. (Original) The method of Claim 16, wherein the relative bias, \bar{x} , of the cost function is a functional bias.
19. (Original) The method of Claim 11, wherein assigning, by a computer, comprises assigning by a processor operable to execute a computer program stored on a computer readable medium.
20. (Original) The method of Claim 11, wherein assigning, by a computer, comprises assigning by an application specific integrated circuit.
21. (Original) The method of Claim 11, wherein assigning, by a computer, comprises assigning by a digital signal processor.

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22. (Currently Amended) A system for assigning observations comprising: a computer readable medium; and

a computer program stored on the computer readable medium, the computer program operable, when executed on a processor, to:

receive a plurality of first observations indicative of respective physical ~~parameters~~ positions observed by a first sensor system and receiving a plurality of second observations indicative of respective physical ~~parameters~~ positions observed by a second sensor system;

assign a set of pairs of the first and second observations predicted to correspond to the same physical ~~parameter~~ position, the assignment comprising:

receiving a cost function that specifies a cost for each assigned pair, the cost not independent of the assignment of any other assigned pairs in the set of assigned pairs; and

determining the set of assigned pairs corresponding to an optimal value for the cost function by calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations.

23. (Original) The system of Claim 22, and further comprising a processor operable to execute the computer program.

24. (Original) The system of Claim 22, wherein the directed graph comprises a plurality of nodes each representing an assignment hypothesis, the plurality of nodes comprising a root node, wherein each node except for the root node has an associated input arc representing an assignment decision and wherein the length of each input arc is representative of a change in an assignment score resulting from the assignment decision, wherein the plurality of nodes are grouped in a plurality of stages.

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25. (Original) The system of Claim 22, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a network shortest path algorithm.

26. (Original) The system of Claim 22, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a Dijkstra algorithm.

27. (Previously Presented) The system of Claim 22, wherein the cost function is

$$J_i = \bar{x}^T R^{-1} \bar{x} - \sum_{i=1}^I \left\{ \frac{\delta x_i^T S_i^{-1} \delta x_i}{g} + \ln[S_i] - \ln(d_{\min}) \begin{matrix} a(i) \neq 0 \\ a(i) = 0 \end{matrix} \right\} + \begin{cases} \ln([2\pi]^M |R|) & n_a = 0 \\ 0 & n_a > 0 \end{cases}$$

wherein J_i = Assignment score
 \bar{x} = Estimate of relative bias
 R = Relative registration covariance matrix
 δx_i = State vector difference = $A_i - B_{a(i)} - \bar{x}$
 S_i = Residual error covariance for pair A_i and $B_{a(i)}$
 d_{\min} = Minimum determinant of a residual error matrix
 g = Gate value
 M = Number of first observations
 n_a = Number of non-zero entries in a
 a = Assignment vector: $a_{(i)} > 0 \rightarrow A_i$ is assigned to $B_{a(i)}$
 A_i = The plurality of first observations

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$B_{a(i)}$ = The plurality of second observations assigned to A_i

28. (Original) The system of Claim 27, wherein the relative bias, x , of the cost function is a simple bias.

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35. (Original) The system of Claim 29, wherein the computer comprises a means for computing.

36. (Original) The system of Claim 29, wherein the directed graph comprises a plurality of nodes each representing an assignment hypothesis, the plurality of nodes comprising a root node, wherein each node except for the root node has an associated input arc representing an assignment decision and wherein the length of each input arc is representative of a change in an assignment score resulting from the assignment decision, wherein the plurality of nodes are grouped in a plurality of stages.

37. (Original) The system of Claim 29, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a network shortest path algorithm.

38. (Original) The system of Claim 29, wherein calculating, by the computer, a corresponding optimal value for a directed graph representative of possible assignments of first and second observations comprises calculating the optimal value by a Dijkstra algorithm.

39. (Previously Presented) The system of Claim 26, wherein the cost function is

$$J_i - \bar{x}^T R^{-1} \bar{x} - \sum_{i=1}^I \left\{ \frac{\delta x_i^T S_i^{-1} \delta x_i + \ln \|S_i\| - \ln(d_{\min})}{\bar{g}} \begin{matrix} a(i) \neq 0 \\ a(i) = 0 \end{matrix} \right\} + \begin{cases} \ln([2\pi]^M |R|) & n_a = 0 \\ 0 & n_a > 0 \end{cases}$$

wherein J_i = Assignment score
 \bar{x} = Estimate of relative bias

R = Relative registration covariance matrix

δx_i = State vector difference = $A_i - B_{a(i)} - \bar{x}$

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- S_i = Residual error covariance for pair A_i and $B_{a(i)}$
- \hat{q}_{min} = Minimum determinant of a residual error matrix
- g = Gate value
- M = Number of first observations
- n_a = Number of non-zero entries in a
- a = Assignment vector: $a_{(i)} > 0 \rightarrow A_i$ is assigned to $B_{a(i)}$
- A_i = The plurality of first observations
- $B_{a(i)}$ = The plurality of second observations assigned to A_i

40. (Original) The system of Claim 39, wherein the relative bias, x , of the cost function is a simple bias.

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